

Overview

In this project we used a densely connected graphical model to detect building rooftops in satellite imagery. Specifically, we applied a fully connected conditional random field defined on the complete set of pixels of an image as proposed by Krahenbuhl et al. [1], with unary potentials derived from Shotton et al.'s TextonBoost [2]. Inference in this model is made tractable by using mean-field approximation and using Gaussian kernels for the pairwise potentials, allowing for an efficient message-passing algorithm.

Model

Traditionally Square-Lattice Ising models have been used for image segmentation. This means we only have edges between neighboring pixels. This method fails to model longer range interactions between nodes, and leads to excessive smoothing. Some researchers have used higher order potentials to combat this problem, and others have created fully connected models on superpixels. Instead we a used dense CRF which has edges between all pixels.



Adjacency CRF

The energy for our model is:

$$E(\mathbf{x}) = \sum_{i} \underbrace{\psi_{u}(x_{i})}_{\text{unary term}} + \sum_{i} \sum_{j>i} \underbrace{\psi_{p}(x_{i}, x_{j})}_{\text{pairwise term}}$$

Where the pairwise potential is defined as:

$$\psi_p(\mathbf{x}_i, \mathbf{x}_j) = \mu(\mathbf{x}_i, \mathbf{x}_j) \sum_{m=1}^{\kappa} w^{(m)} k^{(m)}(\mathbf{f}_i, \mathbf{f}_j)$$

 μ is the label compatibility function and the $k^{(m)}$ are the Gaussian kernels. For the label compatibility function we use the simple Potts model:

$$\mu(x_i, x_j) = [x_i \neq x_j]$$

The specific kernels we use are (I is color intensity, p is position):

$$k(\mathbf{f}_{i}, \mathbf{f}_{j}) = w^{(1)} \underbrace{\exp\left(-\frac{|p_{i} - p_{j}|^{2}}{2\theta_{\alpha}^{2}} - \frac{|I_{i} - I_{j}|^{2}}{2\theta_{\beta}^{2}}\right)}_{\text{appearance kernel}} + w^{(2)} \underbrace{\exp\left(-\frac{|p_{i} - p_{j}|^{2}}{2\theta_{\gamma}^{2}}\right)}_{\text{smoothness kernel}}$$

The unary potentials are learned with TextonBoost as well as HOG, color, and spatial location features as proposed by Ladicky et al. [3].

Dense CRF for Satellite Images Pedro Amaral, Raphael Townshend, and Avideh Zakhor UC Berkeley

Test Results



Original Image



Ground Truth



TextonBoost Output



Dense CRF Output



Original Image



Ground Truth



Original Image



Ground Truth



TextonBoost Output



Dense CRF Output



TextonBoost Output



Dense CRF Output

Precision and Recall

Approach	Pix Prec	Pix Rec	Bld Prec	Bld Rec	# Bldgs
Lefevre	63.60%	79.40%	Х	Х	Х
Muller	77.3%	79.5%	Х	Х	240
Persson	53.0%	93.0%	82.0%	Х	17
Sirmacek	Х	Х	86.6%	Х	177
Liu	Х	Х	94.5%	83.4%	277
enediktsson	80.0%	Х	Х	Х	8952
Shorter	78.7%	51.6%	55.4%	48.2%	2643
Ours	85.0%	58.0%	92.0%	56.0%	1600







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Dataset

Due to the lack of standardized datasets for building segmentation, we collected our own dataset using OpenStreetMap. Due to limitations in satellite geolocation accuracy, a limited amount of post-processing (30 minutes) was needed to allow for pixel-level accuracy. There are 1600 buildings labeled, along with road network data.



OpenStreetMap

Future Work

se Krahhenbuhl et al.'s efficient learning algoritms to learn parameters of the dense CRF

egrate height and road network data into the model force rectangularity constraints on building detections itomate correction of ground truth data collection so that penStreetMap can be harnessed automatically and the taset size increased

Conclusion

ely connected CRF models allow for modeling of long range actions and combat the problem of excessive smoothing. ence can be efficiently performed on this model via the use ean field inference and Gaussian kernels. Our work shows his model can perform well in the field of remote sensing, nore specifically in the problem of building detection.

References

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